

**AMENDMENTS TO ABSTRACT**

Please **delete** the Abstract in its entirety and substitute therefor the following new Abstract.

A manipulator having a bending action member, a front end portion of which includes a multi-slider linkage mechanism which starts the operation of a second articulation portion at its rear end side after the bending action of a first articulation portion on a front end side ends. In the multi-slider linkage mechanism, two frames at a joint portion are formed in forward taper to set the magnitude of a moment required for starting the bending action of a second articulation portion larger than a moment required for the bending action of the first articulation portion. The manipulator includes an actuator and a bending forceps that engage/disengage each other. A guide link portion which covers a link member to guide it through a sliding contact is sealed in a hollow portion to prevent leakage of air.